

Article Info

Received: 01 Jan 2014 | Revised Submission: 20 Feb 2014 | Accepted: 28 Feb 2014 | Available Online: 15 Mar 2014

Microcontroller Based Under/Over Frequency Relay for Power System Protection

Akshy Kumar*, Gaurav Mishra**, Nandini Asthana***, Atul Kumar Yadav****, Mayur Agarwa*****

ABSTRACT

This paper investigates the frequency fluctuation in power system and protect the power system from its harmful effects. Therefore we design a Microcontroller Based Under/Over Frequency Relay. In this paper we use microcontroller AT89S52 for protecting the power system from the problem of frequency fluctuation. When frequency goes below or above from desired value then electromagnetic relay trip and isolate our power system from its harmful effect. Electromechanical protective relays operate by either magnetic attraction, or magnetic induction. Frequency Variation also decrease the life of the equipment and directly affect the overall production of the plant.

Keywords: Frequency Relay; Microcontroller; Trip; CMOS Technology ULN2003.

1.0 Introduction

During severe emergencies which result in insufficient generation to meet load, an automatic load shedding program throughout the affected area can prevent total area collapse. It also helps to achieve fast restoration of all affected loads. This paper describes the factors involved in applying underfrequency and over frequency relays to achieve a desired "deficient generation" protection level and a calculating method to achieve optimum relay settings. When generator operates with under frequency and over frequency mostly its speed matches with resonance frequency which causes high vibration in generator and turbine. So generator do not operates with under frequency. Under overloading condition the generator will slow down to try to accommodate the extra load, this will result in overheating of stator windings, while also under this condition (under frequency) some equipment can be damaged. A load shedding scheme using dedicated frequency sensing relays will trip (disconnect) a set of load from the grid to recover from under freq and stabilize the system avoiding damage to generator and connected equipments.

2.0 Need of Maintaining Frequency Constant

Constant frequency is to be maintained for following functions:

- All ac motors require constant frequency supply to maintain constant speed.
- For synchronous operation of various units in the power system network, it is necessary to maintain constant frequency.
- Frequency affects amount of power transmitted through interconnected lines. So it necessary to maintain constant frequency.
- Electrical clocks will lose or gain time if they are driven by synchronous motor and accuracy of clocks depends on frequency.

3.0 Discription of Block Diagram

We can give an overview of complete operation with the help of microcontroller AT89s52, Electromechanical relay, driver ULN2003 etc.

In this block diagram microcontroller (AT89S52) for control card gets two supply one is the main power supply for their operation and other is the input main ac for variation in frequency. LCD display the operating frequency. Driver is used for driving the relay, LED and buzzer.

*Corresponding Author: Department of Electrical and Electronics Engineering, MIT Moradabad, Uttar Pradesh, India (E-mail: akshayrathore22@gmail.com)

**Department of Electrical and Electronics Engineering, MIT Moradabad, Uttar Pradesh, India

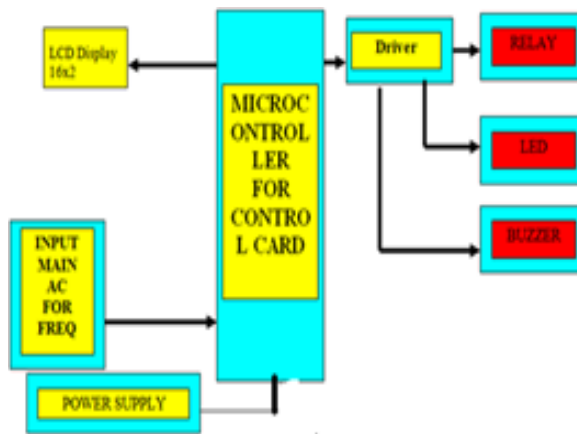
***Department of Electrical and Electronics Engineering, MIT Moradabad, Uttar Pradesh, India

****Department of Electrical and Electronics Engineering, MIT Moradabad, Uttar Pradesh, India

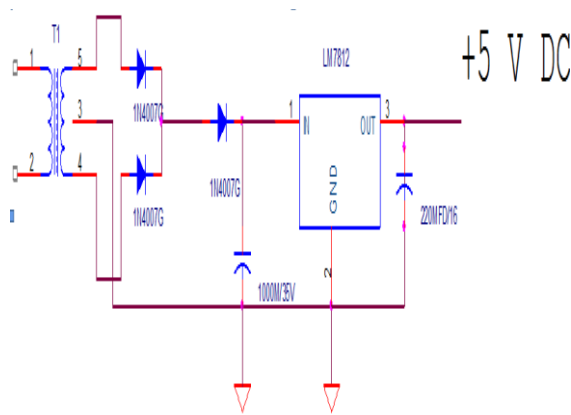
*****Department of Electrical and Electronics Engineering, MIT Moradabad, Uttar Pradesh, India

When frequency goes less or above from our desired value then relay trips in respond to which LED start glowing and buzzer start producing noise to aware operators.

Fig 1: Block Diagram of Under/Over Frequency Relay



4.0 Power Supply



The power supply circuit consists of a bridge rectifier with shunt capacitance filter. A 5 volts regulated source is used for the entire circuit. Three terminal voltage regulators IC 7805 is used to provide 5 volts supply.

4.1 Need of Power Supply

Perhaps all of you are aware that a „power supply“ is a primary requirement for the „Test Bench“ of a home experimenter’s mini lab. A battery eliminator can eliminate or replace the batteries of solid-state electronic equipment and the equipment thus can be operated by 230v A.C. mains instead of

the batteries or dry cells. Nowadays, the use of commercial battery eliminator or power supply unit has become increasingly popular as power source for household appliances like transreceivers, record player, cassette players, digital clock etc.

4.2 Use of DIODES in RECTIFIERS

Electric energy is available in homes and industries in India, in the form of alternating voltage. The supply has a voltage of 220V (rms) at a frequency of 50 Hz. In the USA, it is 110V at 60 Hz. For the operation of most of the devices in electronic equipment, a dc voltage is needed. For instance, a transistor radio requires a dc supply for its operation. Usually, this supply is provided by dry cells. But sometime we use a battery eliminator in place of dry cells. The battery eliminator converts the ac voltage into dc voltage and thus eliminates the need for dry cells. Nowadays, almost all-electronic equipment includes a circuit that converts ac voltage of mains supply into dc voltage. This part of the equipment is called Power Supply. In general, at the input of the power supply, there is a power transformer. It is followed by a diode circuit called Rectifier. The output of the rectifier goes to a smoothing filter, and then to a voltage regulator circuit. The rectifier circuit is the heart of a power supply.

4.3 Filtration

The rectifier circuits we have discussed above deliver an output voltage that always has the same polarity: but however, this output is not suitable as DC power supply for solid-state circuits. This is due to the pulsation or ripples of the output voltage. This should be removed out before the output voltage can be supplied to any circuit. This smoothing is done by incorporating filter networks. The filter network consists of inductors and capacitors. The inductors or choke coils are generally connected in series with the rectifier output and the load. The inductors oppose any change in the magnitude of a current flowing through them by storing up energy in a magnetic field. An inductor offers very low resistance for DC whereas; it offers very high resistance to AC. Thus, a series connected choke coil in a rectifier circuit helps to reduce the pulsations or ripples to a great extent in the output voltage. The filter capacitors are usually connected in parallel with the rectifier output and the load. As, AC

can pass through a capacitor but DC cannot, the ripples are thus limited and the output becomes smoothed. When the voltage across its plates tends to rise, it stores up energy back into voltage and current. Thus, the fluctuations in the output voltage are reduced considerably. Filter network circuits may be of two types in general: Choke Input Filter, Capacitor Input Filter.

5.0 Circuit Diagram

We can see the complete operation of this paper with the help of this circuit diagram. In this circuit diagram

Fig. 2. Circuit Diagram of Under/Over Frequency Relay

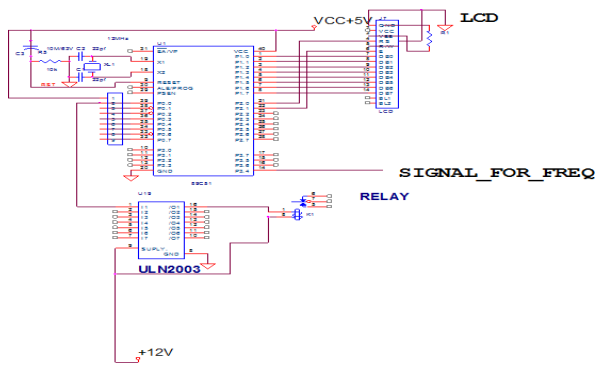


Fig. 3. Picture of Under/Over Frequency Relay



6.0 Description of Microcontroller AT89S52

Microcontroller AT89S52 which are used for controlling the frequency deviation. The AT89S52 is a low-power, high-performance CMOS 8-bit microcontroller with 8K bytes of in-system programmable Flash memory. The device is

manufactured using Atmel's high-density nonvolatile memory technology and is compatible with the industry-standard 80C51 instruction set and pinout. The on-chip Flash allows the program memory to be reprogrammed in-system or by a conventional nonvolatile memory programmer. By combining a versatile 8-bit CPU with in-system programmable Flash on a monolithic chip, the Atmel AT89S52 is a powerful microcontroller which provides a highly-flexible and cost-effective solution to many embedded control applications. The AT89S52 provides the following standard features: 8K bytes of Flash, 256 bytes of RAM, 32 I/O lines, Watchdog timer, two data pointers, three 16-bit timer/counters, a six-vector two-level interrupt architecture, a full duplex serial port, on-chip oscillator, and clock circuitry. In addition, the AT89S52 is designed with static logic for operation down to zero frequency and supports two software selectable power saving modes. The Idle Mode stops the CPU while allowing the RAM, timer/counters, serial port, and interrupt system to continue functioning. The Power-down mode saves the RAM contents but freezes the oscillator, disabling all other chip functions until the next interrupt or hardware reset.

(T2) P1.0	1	40	VCC
(T2 EX) P1.1	2	39	P0.0 (AD0)
P1.2	3	38	P0.1 (AD1)
P1.3	4	37	P0.2 (AD2)
P1.4	5	36	P0.3 (AD3)
(MOSI) P1.5	6	35	P0.4 (AD4)
(MISO) P1.6	7	34	P0.5 (AD5)
(SCK) P1.7	8	33	P0.6 (AD6)
RST	9	32	P0.7 (AD7)
(RXD) P3.0	10	31	EA/VPP
(TXD) P3.1	11	30	ALE/PROG
(INT0) P3.2	12	29	PSEN
(INT1) P3.3	13	28	P2.7 (A15)
(T0) P3.4	14	27	P2.6 (A14)
(T1) P3.5	15	26	P2.5 (A13)
(WR) P3.6	16	25	P2.4 (A12)
(RD) P3.7	17	24	P2.3 (A11)
XTAL2	18	23	P2.2 (A10)
XTAL1	19	22	P2.1 (A9)
GND	20	21	P2.0 (A8)

7.0 Relay

A **relay** is an electrical switch that opens and closes under the control of another electrical circuit. In the original form, the switch is operated by an electromagnet to open or close one or many sets of contacts. Because a relay is able to control an output circuit of higher power than the input circuit, it can be considered, in a broad sense, to be a form of an electrical amplifier. When a current flows through the coil, the resulting magnetic field attracts an armature

that is mechanically linked to a moving contact. The movement either makes or breaks a connection with a fixed contact. . When the current to the coil is switched off, the armature is returned by a force approximately half as strong as the magnetic force to its relaxed position. Most relays are manufactured to operate quickly. In a low voltage application, this is to reduce noise. In a high voltage or high current application, this is to reduce arcing.

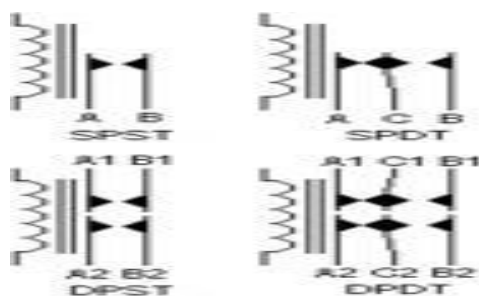
8.0 Pole & Throw

SPST – Single Pole Single Throw These have two terminals which can be switched on/off. In total, four terminals when the coil is also included

SPDT - Single Pole Double Throw. These have one row of three terminals. One terminal (common) switches between the other two poles. It is the same as a single change-over switch. In total, five terminals when the coil is also included

DPST - Double Pole Single Throw These have two pairs of terminals. Equivalent to two SPST switches or relays actuated by a single coil. In total, six terminals when the coil is also included. This configuration may also be referred to as DPNO

Fig. 3. Circuit symbols of relays



The contacts can be either **Normally Open (NO)**, **Normally Closed (NC)**, or **change-over (CO)** contacts

9.0 Applications

Frequency relays are used whenever deviations from nominal system frequency need to be detected. Frequency deviations can be harmful to connected objects, such as generators and motors, or when abnormal frequency creates inconvenience for power consumers and may cause failures of electrical apparatuses. Frequency relays are also used where detection of high or low frequency indicates system abnormalities, such as faults in speed regulation units or system overload. Under frequency relays should be

considered for applications where the detection of under speed conditions for synchronous motors and condensers is required. On lines where reclosing of the source breaker is utilized, damage to large synchronous motors can be avoided by disconnecting the motors from the system. Likewise, disconnection of synchronous condensers can be initiated upon loss of power supply. The over frequency relay is generally utilized for the protection of ac machines from possible damage due to over speed conditions. These conditions can occur, for example, on machines with no mechanical governor or on those with the machine shaft linked to a prime mover or to another machine, either one of which could accelerate the combination to a hazardous over speed condition (e.g. a hydrogenerator).

10.0 Conclusion

At last we would like to conclude this paper under the guidance of highly capable mentor along with group members. Basically it is not just a paper it is the need of our initiative should be taken up to implement this practically in the college environment and the research is continued further by the students with maintenance. Future aspects of this paper is to be mainly used in chemical industries, protection of transformers and generators in power system which might be badly affected by frequency variation. Also the life and performance of equipment suffers due to frequency variation.

References

- [1] Jose C. M. Vieira, Waldir Freitas, Wilsun Xu, Andre Morelato, "Performance of Frequency Relays for Distributed Generation Protection," IEEE Transactions On Power Delivery, 21(3), 2006
- [2] Uchhrang K. Jethwa, Rajeev Kumar Bansal, Ninad Date, and Ranjeet Vaishnav, "Comprehensive Load-Shedding System," IEEE Transactions On Industry Applications, 46(2), 2010
- [3] Electrical Power Systems by C. L. Wadhwa, "New Age International Publishers Limited", New Delhi, 2009.
- [4] Modern Power System Analysis by Kothari and Nagrath "TMH Publication."